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## WHAT IS CLAIMED IS:

1. A method for controlling the idle speed of an engine within a hybrid electric vehicle including a generator having a rotor assembly which is operatively coupled to an engine, said method comprising the steps of:

determining whether a first set of vehicle idle entry conditions are met, wherein said first set of vehicle idle entry conditions comprises whether the vehicle is below a predetermined maximum idle speed and whether an accelerator pedal is below a predetermined minimum pedal position;

scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed and producing a first desired effect when a first set of operating conditions is present:

selectively activating an engine controller to control engine idle speed when a second set of operating conditions is present; and

turning off the engine when said first set of conditions is not present and when the engine has

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been in a current vehicle idle mode for a predetermined amount of time.

- 2. The method of claim 1, wherein the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed and producing a first desired effect when a first set of operating conditions is present comprises the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed to produce a first desired effect when a state of charge of a battery is below a predetermined battery minimum state of charge.
- 3. The method of claim 1, wherein the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed and producing a first desired effect when a first set of operating conditions is present comprises the step of scheduling a desired engine brake torque and selectively activating a vehicle

system controller to control said generator to schedule a desired engine speed to produce a first desired effect when a vacuum level in a climate control reservoir is below a predetermined minimum climate control vacuum level.

- 4. The method of claim 1, wherein the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed and producing a first desired effect when a first set of operating conditions is present comprises the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed to produce a first desired effect when a vacuum level in a brake system reservoir is below a predetermined brake system vacuum level.
- 5. The method of claim 1, wherein the

  20 step of scheduling a desired engine brake torque and
  selectively activating a vehicle system controller to
  control said generator to schedule a desired engine
  speed and producing a first desired effect when a

first set of operating conditions is present comprises the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed to produce a first desired effect when a vacuum level in a powertrain vacuum mount reservoir is below a predetermined minimum powertrain mount vacuum level.

- 6. The method of claim 1, wherein the
  step of scheduling a desired engine brake torque and
  selectively activating a vehicle system controller to
  control said generator to schedule a desired engine
  speed and producing a first desired effect when a
  first set of operating conditions is present
  comprises the step of scheduling a desired engine
  brake torque and selectively activating a vehicle
  system controller to control said generator to
  schedule a desired engine speed to produce a first
  desired effect when a vapor canister contained within
  a fuel system requires purging.
  - 7. The method of claim 1, wherein the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to

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control said generator to schedule a desired engine speed and producing a first desired effect when a first set of operating conditions is present comprises the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed to produce a first desired effect when an adaptive fuel table requires HEV-fast adaptive learning.

- 8. The method of claim 1, wherein the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed and producing a first desired effect when a first set of operating conditions is present comprises the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed to produce a first desired effect when the engine has cooled below a predetermined engine temperature.
  - 9. The method of claim 1, wherein the step of scheduling a desired engine brake torque and

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selectively activating a vehicle system controller to control said generator to schedule a desired engine speed and producing a first desired effect when a first set of operating conditions is present comprises the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed to produce a first desired effect when a catalyst has cooled below a predetermined minimum catalyst temperature.

10. The method of claim 1, wherein the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed and producing a first desired effect when a first set of operating conditions is present comprises the step of scheduling a desired engine brake torque and selectively activating a vehicle system controller to control said generator to schedule a desired engine speed to produce a first desired effect when air conditioning has been requested by a vehicle operator.

11. The method of claim 1, wherein the step of selectively activating an engine controller to control engine idle speed when a second set of operating conditions is present comprises the step of selectively activating an engine controller to control engine idle speed when:

the generator has failed; or

a battery state of charge exceeds a maximum desired level

10 12. A hybrid electric vehicle including a generator having a rotor assembly which is operatively coupled to an engine, the hybrid electric vehicle comprising:

a vehicle system controller for controlling

15 the idle speed of the engine when a first set of
operating conditions is present at a scheduled engine
brake torque to produce a desired result; and

an engine controller for controlling the idle speed of the engine when a second set of 20 operating conditions is present.

13. The method according to claim 11, wherein said first set of operating conditions is selected from a group consisting of a low battery

state of charge, a low climate control vacuum level, a low brake system reservoir vacuum level, a low powertrain mount vacuum level, a high fuel tank vapor pressure requiring fuel vapor canister purging, a condition where the fuel vapor canister is currently being purged, a minimum time reached since previously purging the vapor canister, a low engine temperature, a low catalyst temperature, an adaptive fuel table requiring HEV-fast adaptive learning, and an activated air conditioning switch.

- 14. The hybrid electric vehicle of claim
  12, wherein said second set of operating conditions
  is selected from a group consisting of a high battery
  state of charge and a failed generator.
- 15. A method for controlling the idle speed of an engine within a hybrid electric vehicle including a generator having a rotor assembly which is operatively coupled to an engine, said method comprising the steps of:
- determining whether a first set of vehicle idle entry conditions are met, wherein said first set of vehicle idle entry conditions comprises whether the vehicle is below a predetermined maximum idle

speed and whether an accelerator pedal is below a predetermined minimum pedal position;

scheduling a desired engine brake torque and selectively activating a vehicle controller to control said generator to schedule a desired engine speed and produce a first desired effect when a first set of operating conditions is present, wherein said first set of operating conditions is selected from the group consisting of a 10 low battery state of charge, a low climate control vacuum level, a low brake system reservoir vacuum level, a low powertrain mount vacuum level, a high fuel tank pressure, the existence of a minimum time period since a last vapor canister purging, 15 existence of current vapor canister purging, existence of a learned adaptive fuel table for the current driving mode, a low engine temperature, a low catalyst temperature, and the state of activation of an air conditioning switch;

selectively activating an engine controller to control engine idle speed when a second set of operating conditions is present;

turning off the engine when said first set of conditions is not present and when the engine has

been in a current vehicle idle mode for a predetermined amount of time, otherwise maintaining said current vehicle idle mode.

16. The method of claim 15, wherein the step of selectively activating an engine controller to control engine idle speed when a second set of operating conditions is present comprises the step of selectively activating an engine controller to control engine idle speed when:

the generator has failed; or

 $\label{eq:abstraction} a \ \text{battery state of charge exceeds a maximum} \\$  desired level.